GPS Update:

With Arduino Uno:

* Location (latitude and Longitude) - accurate
* Speed (knots)
* Altitude (in meters)
* Angle (‘compass’ direction)
* Time/date

Unfortunately, A lot of junk is returned as well

{Set-up: 5V to 5V, GND to GND, RX on GPS to pin 2, TX on GPS to pin 3}

BNO IMU Sensor Update:

With Arduino Uno:

* Current Ambient Temperature (Degrees Celsius)
* Quaternion
* Euler Angles
* Orientation Data

{Set-up: VIN to 5V, GND to GND, Sensor SDA to A4, Sensor SCL to A5}

Valves Update: